WHAT IS CLAIMED IS

1. A method of operating an underground or inaccessible object, said object including a sonde arranged to emit signals having a plurality of non-orientation-dependent characteristics, said method comprising the steps of;

applying a predetermined rotation sequence involving at least one rotation step to said object;

detecting said rotation sequence;

wherein said detection of said rotation sequence causes said sonde to change from the emission of a first signal having a first non-orientation-dependent characteristic to the emission of a second signal having a second non-orientation-dependent characteristic.

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- 2. A method according to claim 1 wherein said first non-orientation-dependent characteristic and said second non-orientation-dependent characteristic of said signal are a first carrier frequency and a second carrier
- 20 frequency respectively.
 - 3. A method according to claim 1 wherein said first non-orientation-dependent characteristic and said second non-orientation-dependent characteristic of said signal are a first data output sequence and a second data output
- 25 are a first data output sequence and a second data output sequence respectively.

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- 4. A method according to claim 1 wherein said first non-orientation-dependent characteristic and said second non-orientation-dependent characteristic of said signal are a first data transfer rate and a second data transfer rate respectively.
- A method according to claim 1 wherein said first non-orientation-dependent characteristic and said second
 non-orientation-dependent characteristic of said signal are a first output power and a second output power respectively.
- A method according to any one of the preceding
 claims wherein said rotation sequence comprises a plurality of rotation steps.
 - 7. A method according to claim 6 wherein each rotation of said plurality of steps is completed within a predetermined time limit.
 - 8. A method according to any one of the preceding claims wherein said object is an underground boring tool.
- 25 9. Apparatus for operating an underground or inaccessible object, said apparatus including including;

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a sonde for emitting a plurality of signals having predetermined non-orientation-dependent characteristics;

rotation means for applying a predetermined rotation sequence involving at least one rotation step to said object;

detection means for detecting said predetermined rotation sequence; and

response means activated by said detection of said predetermined rotation sequence for causing said sonde to change from the emission of a first signal having a first non-orientation-dependent characteristic to the emission of a second signal being a second non-orientation-dependent characteristic.

- 15 10. Apparatus according to claim 8 wherein said object is an underground boring tool and said detection means is a roll sensor.
- 11. A method of operating an underground or inaccessible object including a sonde, said object being connected to an operator triggered drive means

said method comprising the steps of;

signalling from said drive means to said sonde, said signalling including the operator triggering said

operator triggered drive means to apply a predetermined rotation sequence involving at least one rotation step to

said object;

detecting said rotation sequence;
wherein said detection of said rotation sequence causes
said sonde to change from a first operation function to a
second operation function.

- 12. A method according claim 11 wherein said rotation sequence comprises a plurality of rotation steps.
- 10 13. A method according to claim 12 wherein each rotation of said plurality of steps is completed within a predetermined time limit.
 - 14. Apparatus for operating an underground or
- 15 inaccessible object including;

a sonde;

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operator-triggered drive means connected to said object for applying a predetermined rotation sequence involving at least one rotation step to the object to signal to said object in response to a trigger from the operator;

detection means for detecting said rotation sequence; and

response means activated by the detection of said
25 predetermined rotation sequence for causing said sonde to
change from a first operation function to a second

operation function.